## **DevCNC\_Foam setup instructions**

Download, install and run Arduino IDE from the below link <u>https://www.arduino.cc/en/software</u>

Download and install DevCNCFoam from the below link <a href="https://www.devcad.com/download/DevCncFoamSetup1\_06b.exe">https://www.devcad.com/download/DevCncFoamSetup1\_06b.exe</a>

RunDevCNC and follow the settings as in the pictures below Select the correct driver board "Arduino Mega2560 + Ramps 1.4" Click on the auto Detect - if the computer detected the port, continue to the next step, If the program did not detect the port, make sure that the USB cable is connected And that the the Arduino IDE was installed.

devCnc Foam				
Load Start Pause Start Rewind			3D 🕅 🖗 🖗 🌔 Ortho 🚱 🎼 🔄 😫	
Lett carage: XL: 0.919 / YL: 2.872 / SC: 0.000 SF: 0.0000 SF: 0.0000 SF: 0.000 SF: 0.000 SF: 0.000 SF	Feed speed rectime override K: 0.039 1.●	Sctings Controller and output pire Controller and output pire Controller and output pire Controller Spred Controller Spred Controller Spred Controller Controller Spred Controller Contr	traller and output pine fertype: Acutinu Meys2560 + Rango 1.4 upd pro. Step Dr E Stor axis YL: 54 25 7 Xor axis YL: 60 61 7 Xor axis YL: 60 61 48 6 Xor axis YR: 26 28 7 Xor axis YR: 26 28 7 Xor axis YR: 26 28 7 Sol default Pin values for the Sol default Pin values for the S	able Hard Lints switches

Once done, click on the Apply button

devCnc Foam		
File Recording Settings Help		
🛥 Load 🕟 Start 💷 Pause	3D 🕎 🚱	😥 🔕 Orthu
Stop Rewind		♥ 🚅 📲
Let cariage: XI: -0.019 XI: XI: -4.436 XI: XI: -1.683 XI: XI: XI: -1.683 XI: XI: XI: -1.683 XI: XI: XI: XI: XI: XI:	Field speed realine overlide:   Image: Settings   Settings   Image: Seting   Image: Set	E centre Min An SCode comands about units settings d at nex "Load Goods" command a: etem/Min tin DK Cancel Activ Hep

Select the Units button and set both the Inches

devCnc Foam									
File Recording Settings Help									
🖻 Load 🕟 Start 🔘 Pause			3D 🕈 ŷ	<b>Ø</b>	Ortho				
Ston @ Dowind				🛛 🚅					
Stop Grewing									
Left carriage: Right carriage	- Food spood realtime overrids:								
XL: -0.919 🖍 XR: -4.436 🖍	K: 0.039								
YL: -2.872 🖉 YR: -1.683 🖉	1 •								
SC: 0.000 SC: 0.000		Settings							×
SF: 0.000 SF: 0.000		Controller and output pins	🖨 Motors						
K + 7 K + 7		- Motors	Apply the same setti	ings to all motor	rs				
		GCode	$\mathbf{\hat{h}}$	21	M	VD	VD.		
		-SL Soft Limits	Steps/mm:	800.00	100.00	800.00	800.00		
		Hard Limits (switches)	Mary Daniel Arms Archite	400.00	400.00	1	400.00		
Jog		- Time Keyboard	max. speed (min/min).	400.00	400.00	400.00	400.00		
Jog S. 15.748 🖉 ——			Acceleration (mm/s/s):	16.00	16.00	16 00	16.00		
🗌 Keep Jog rrove Inked		Units	Invert direction:	☐ Invert	🔽 Invert	□ Invert	V Invert		
Emulation			v Invert motors enab	ole (enabled wit	h LOW pin v	itage)			
I Emulation mode			Keen motore alway	veenabled					
			, help hour and	, conduced					
$\Phi$ Set origin here $\downarrow$ Go to origin									
⊙Calibrate origin Restart HAL									
								-	
								JL	
								V	
						ОК	Cancel	Apply	Help
		L						~	

Click on the Motors button and check the "Apply the same settings to all motors Then set the values as in the picture above. When done, click on the Apply button





## for more information please refer to the help file

